

# Current Singularity Formation in Line-tied Magnetic Fields: the Parker Problem

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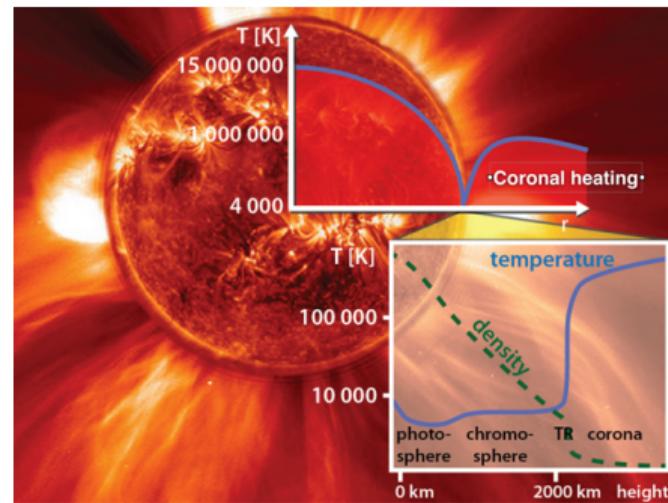
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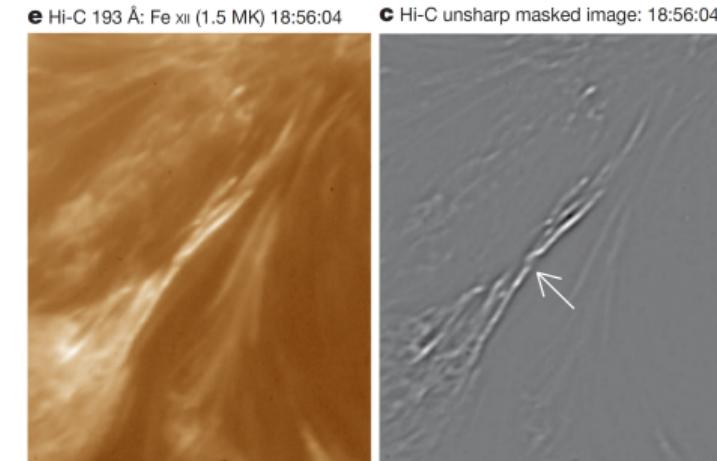
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# Coronal heating by nano-flares

- ‘Conflicting’ features of solar corona:
  - nearly perfect conductivity ( $S \gtrsim 10^{12}$ );
  - very high temperature ( $T \gtrsim 10^6$  K).



- A possible mechanism<sup>1</sup>:
  - current singularities tend to form;
  - then, magnetic reconnection.
- Observational evidence exists<sup>2</sup>.

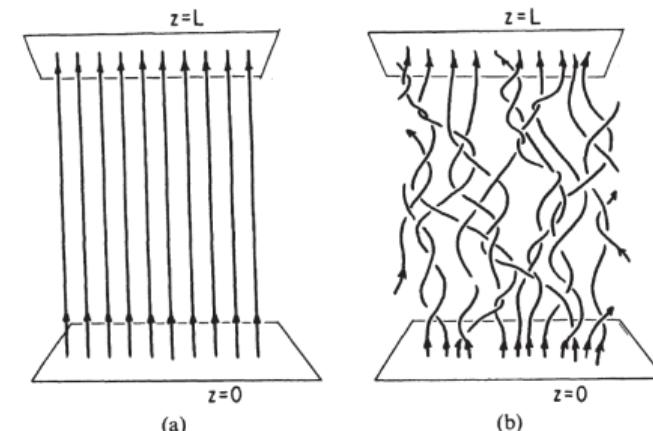


<sup>1</sup>E. N. Parker, *Astrophys. J.* 174, 499 (1972).

<sup>2</sup>J. W. Cirtain et al., *Nature* 493, 501 (2013).

# The Parker problem

- Ideal, mathematical abstraction<sup>3</sup>:
  - can genuine current singularities emerge in 3D line-tied plasmas?
- Practical relevance: tendency matters;
  - if not singular, how thin?
- Line-tied geometry: no closed field lines;
  - unlike toroidal fusion plasmas.
- Challenge: to preserve magnetic topology;
  - both analytically and numerically.
- Still controversial today.



<sup>3</sup>E. N. Parker, *Spontaneous Current Sheets in Magnetic Fields: With Applications to Stellar X-rays* (Oxford University Press, New York, 1994).

# Highlights

- Lagrangian labeling: the favorable description;
  - built-in frozen-in equation;
  - magnetic topology automatically preserved.
- Discretization: ideal MHD on a moving mesh;
  - **no artificial reconnection**, unlike Eulerian methods;
  - variational, with discrete exterior calculus.
- Current singularity formation in 2D: **conclusively** confirmed;
  - the Hahm–Kulsrud–Taylor (HKT) problem;
  - analytical and numerical solutions agree.
- Extension to 3D line-tied geometry: inconclusive;
  - smooth linear solution;
  - smooth nonlinear solution for short systems;
  - scaling **suggests** finite-length singularity.

# Ideal MHD in Lagrangian labeling

- Dynamical variable: fluid configuration map  $\mathbf{x}(\mathbf{x}_0, t)$ . [ $x_{ij} \doteq \partial x_i / \partial x_{0j}$ ,  $J \doteq \det(x_{ij})$ .]
- Advection equations are formally solved:

$$\partial_t \rho + \nabla \cdot (\rho \mathbf{v}) = 0 \Leftrightarrow \rho d^3x = \rho_0 d^3x_0 \Leftrightarrow \rho = \rho_0/J, \quad (1a)$$

$$\partial_t(p/\rho^\gamma) + \mathbf{v} \cdot \nabla(p/\rho^\gamma) = 0 \Leftrightarrow p/\rho^\gamma = p_0/\rho_0^\gamma \Leftrightarrow p = p_0/J^\gamma, \quad (1b)$$

$$\partial_t \mathbf{B} - \nabla \times (\mathbf{v} \times \mathbf{B}) = 0 \Leftrightarrow B_i dS_i = B_{0i} dS_{0i} \Leftrightarrow B_i = x_{ij} B_{0j}/J. \quad (1c)$$

- Then, **built into** the momentum equation:

$$\rho_0 \ddot{x}_i = B_{0j} \frac{\partial}{\partial x_{0j}} \left( \frac{x_{ik} B_{0k}}{J} \right) - \frac{\partial J}{\partial x_{ij}} \frac{\partial}{\partial x_{0j}} \left( \frac{p_0}{J^\gamma} + \frac{x_{kl} x_{km} B_{0l} B_{0m}}{2J^2} \right). \quad (2)$$

- A field theory, with Lagrangian<sup>4</sup>:

$$L[\mathbf{x}] = \int \left[ \frac{1}{2} \rho_0 \dot{x}^2 - \frac{p_0}{(\gamma - 1) J^{\gamma-1}} - \frac{x_{ij} x_{ik} B_{0j} B_{0k}}{2J} \right] d^3x_0. \quad (3)$$

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<sup>4</sup>W. A. Newcomb, Nucl. Fusion 1962, Suppl. 2, 451 (1962)

# Current singularity formation: problem statement

- Customary to study equilibria. (Dynamics can be complicated.)
- Perfectly-conducting plasma: magnetic topology preserved.
- Eulerian equilibrium equation,

$$(\nabla \times \mathbf{B}) \times \mathbf{B} = \nabla p, \quad (4)$$

is underdetermined:

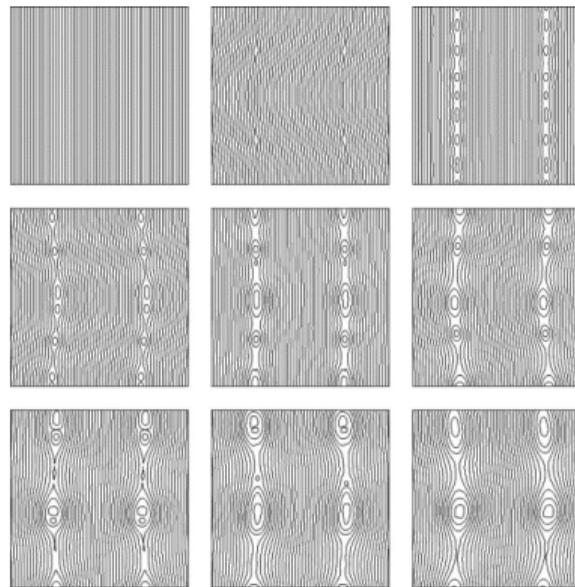
- difficult to attach the topological constraint;
- existence of singularities does not imply formation.
- Lagrangian equilibrium equation has the constraint built-in:

$$B_{0j} \frac{\partial}{\partial x_{0j}} \left( \frac{x_{ik} B_{0k}}{J} \right) = \frac{\partial J}{\partial x_{ij}} \frac{\partial}{\partial x_{0j}} \left( \frac{p_0}{J^\gamma} + \frac{x_{kl} x_{km} B_{0l} B_{0m}}{2J^2} \right). \quad (5)$$

- **Objective:** find solutions with current singularities to Eq. (5), given smooth initial and boundary conditions.

# Ideal MHD on a moving mesh

- Eulerian ideal MHD simulations:
  - artificial reconnection<sup>5</sup>.



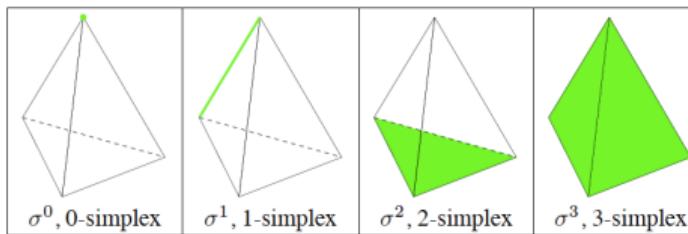
- Discretization in Lagrangian labeling:
  - moving mesh simulates fluid motion;
  - no artificial reconnection.

- Can be done directly<sup>6</sup>, but we shall...

<sup>5</sup>T. A. Gardiner and J. M. Stone, *J. Comput. Phys.* 205, 509 (2005).

<sup>6</sup>I. J. D. Craig and A. D. Sneyd, *Astrophys. J.* 311, 451 (1986).

# Variational integration for ideal MHD



- Discrete exterior calculus (DEC)<sup>7</sup>:
  - discrete manifold;
  - discrete differential forms;
  - discrete Stokes' theorem guarantees  $\nabla \cdot \mathbf{B} = 0, \nabla \cdot \mathbf{j} = 0$ .

- Discretize the Lagrangian:

- conservative many-body form<sup>8</sup>,

$$L(\mathbf{x}, \dot{\mathbf{x}}) = \sum_{\sigma_0^0} \frac{1}{2} M(\sigma_0^0) \dot{x}^2 - W(\mathbf{x}); \quad (6)$$

- discrete equilibrium,  $\partial W / \partial \mathbf{x} = 0$ .

- Add friction for equilibration.
- (Structure-preserving numerical methods in plasma physics<sup>9</sup>: guiding center, PIC...)

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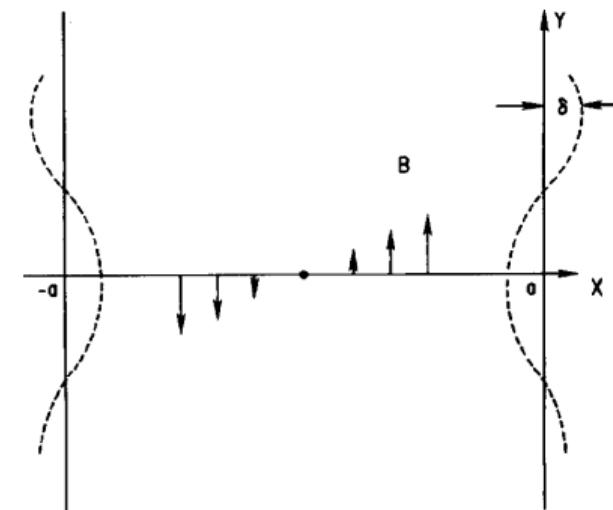
<sup>7</sup>M. Desbrun et al., arXiv:math/0508341 (2005).

<sup>8</sup>Y. Zhou et al., Phys. Plasmas 21, 102109 (2014).

<sup>9</sup>P. J. Morrison, Phys. Plasmas 24, 055502 (2017); J. Xiao et al., Plasma Sci. Technol. 20, 110501 (2018).

# The Hahm–Kulsrud–Taylor (HKT) problem

- Relevance to toroidal fusion plasmas:
  - resonant magnetic perturbations;
  - 3D equilibria with nested surfaces.
- 2D incompressible plasma,  $B_{0y} = x_0$ .
- Mirrored sinusoidal boundary displacement<sup>10</sup>:  $\xi(\pm a, y) = \mp\delta \cos ky$ .
- Multiple known equilibrium solutions<sup>11</sup>:
  - some contain current singularities;
  - magnetic topology not preserved.

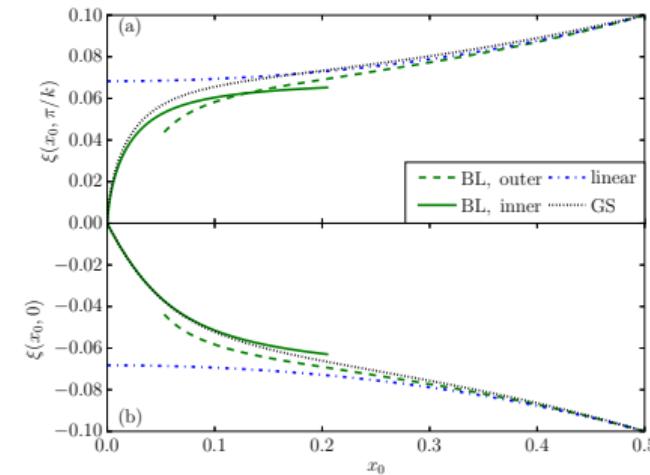
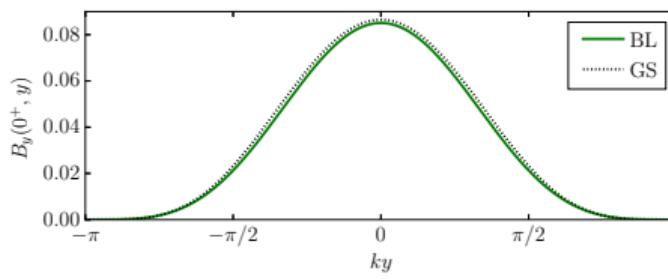


<sup>10</sup>T. S. Hahm and R. M. Kulsrud, Phys. Fluids 28, 2412 (1985).

<sup>11</sup>R. L. Dewar et al., Phys. Plasmas 20, 082103 (2013); J. Loizu et al., Phys. Plasmas 22, 022501 (2015).

# Topologically constrained equilibrium solution

- $\xi$ : Lagrangian displacement.
  - Linear solution: unphysical, discontinuous displacement.
  - Boundary-layer (BL) solution<sup>12</sup>: nonlinear, continuous displacement.
  - Numerical solution: flux-preserving Grad–Shafranov (GS) solver<sup>13</sup>.



- Discontinuous  $\langle B_y \rangle$  but  $\iota \sim \langle B_y^{-1} \rangle^{-1}$ :
  - stays continuous, despite a recent claim<sup>14</sup>.

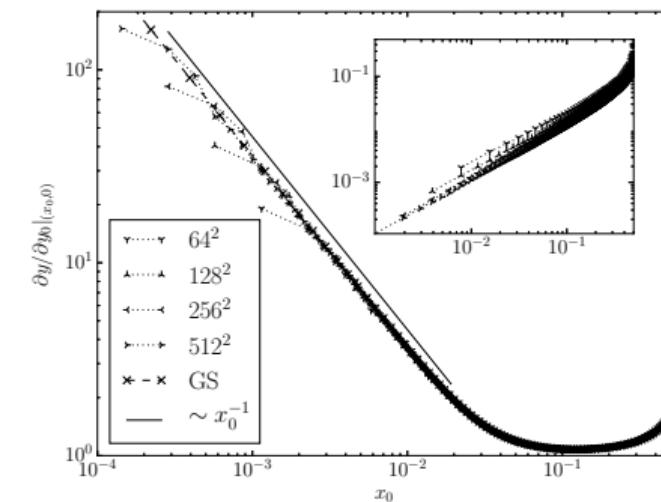
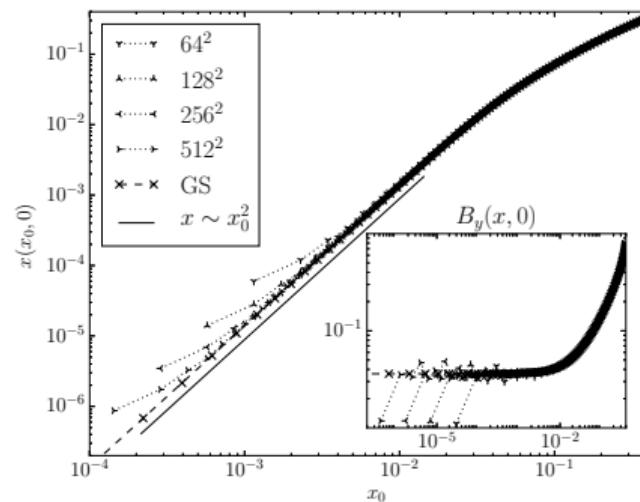
<sup>12</sup>Y. Zhou et al., arXiv:1810.08268 (2018); M. N. Rosenbluth et al., Phys. Fluids 16, 1894 (1973).

<sup>13</sup>Y.-M. Huang et al., Astrophys. J. 699, L144 (2009).

<sup>14</sup>J. Loizu and P. Helander, Phys. Plasmas 24, 040701 (2017).

# Fully Lagrangian solution converges to GS solution

- Normal ( $x$ ) direction, at  $y_0 = 0$ :
  - $x \sim x_0^2$ ,  $B_y = B_{0y}/(\partial x/\partial x_0) \sim \text{sgn}(x)$ ;
  - plasma infinitely compressed<sup>15</sup>.
- $J = 1$  requires tangential ( $y$ ) direction:
  - $\partial y/\partial y_0 \sim x_0^{-1}$ , non-differentiable;
  - plasma infinitely stretched.

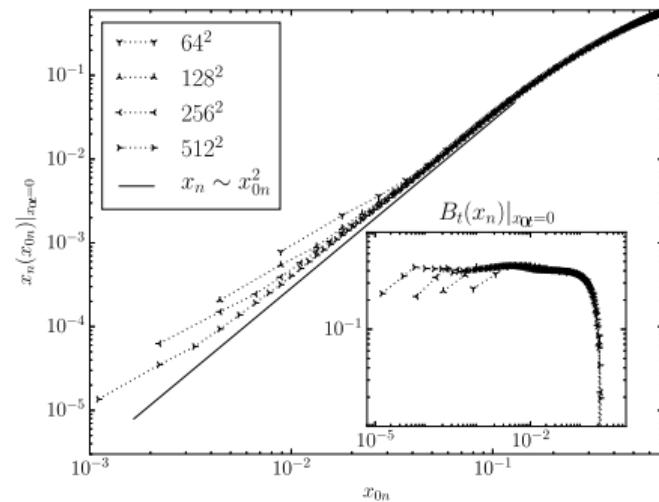


- GS solver: limited applicability. Lagrangian method: more complex topology, 3D.

<sup>15</sup>Y. Zhou et al., Phys. Rev. E 93, 023205 (2016).

# General mechanism for current singularities in 2D

- Coalescence instability of magnetic islands<sup>16</sup>:
  - different drive, more complex topology;
  - same quadratic mapping as in HKT<sup>17</sup>.

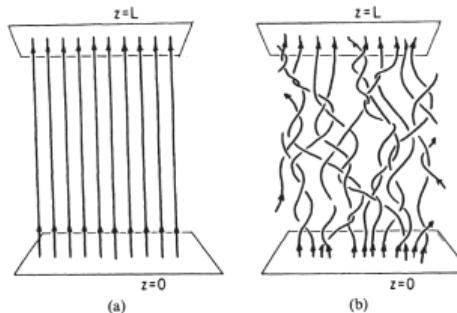


- Recipe: compress a sheared field.
- How about 3D line-tied geometry?

<sup>16</sup>D. W. Longcope and H. R. Strauss, Phys. Fluids B 5, 2858 (1993).

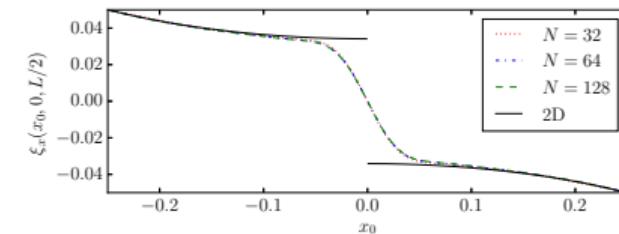
<sup>17</sup>Y. Zhou, Ph.D. thesis, Princeton University, arXiv:1708.08523 (2017).

# Line-tied geometry: smooth linear solution

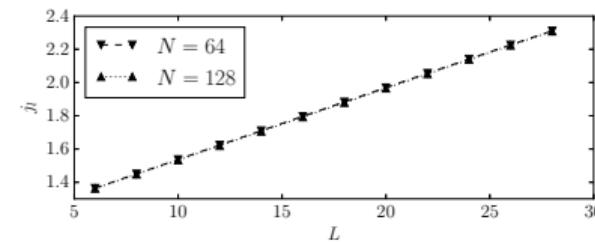


- Parker's original setup:
  - uniform  $\mathbf{B}_0 = \hat{z}$ ;
  - prescribed footpoint motion.
- Our formula:
  - known 'susceptible'  $\mathbf{B}_0$  in 2D;
  - no-slip footpoints;
  - **focus:** effect of line-tying.

- Line-tied HKT: boundary perturbation  $\xi(\pm a, y, z) = \mp\delta \cos ky \sin(\pi z/L)$ .
- Given  $L$ , linear solution is smooth<sup>18</sup>.



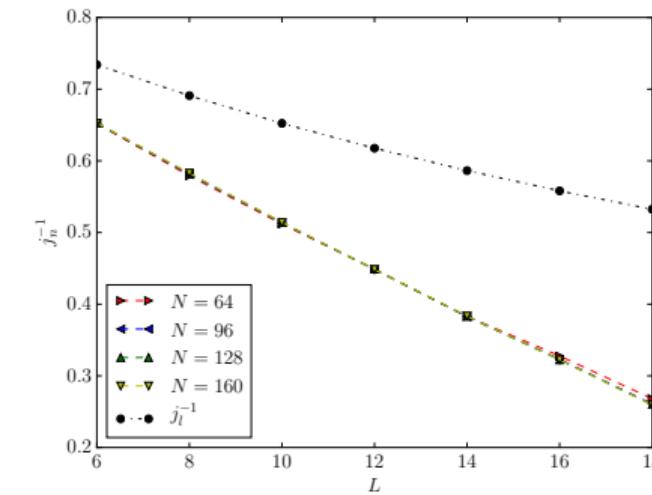
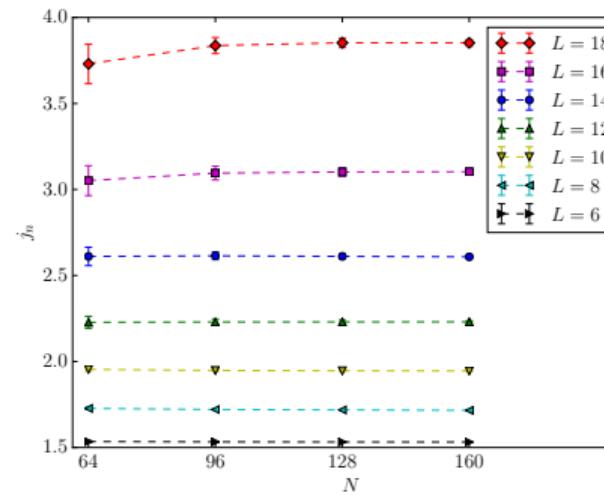
- Current density  $j_l$  scales linearly with  $L$ .



<sup>18</sup>Consistent with E. G. Zweibel and H.-S. Li, *Astrophys. J.* 312, 423 (1987).

# Nonlinear solutions: convergence and scaling

- For short systems, nonlinear solutions are smooth and well-resolved<sup>19</sup>.
- $j_n \sim (L_n - L)^{-1}$ , suggests finite-length singularity:
  - stronger than proposed exponential scaling<sup>20</sup>;
  - echoes existing analytical theory<sup>21</sup>.

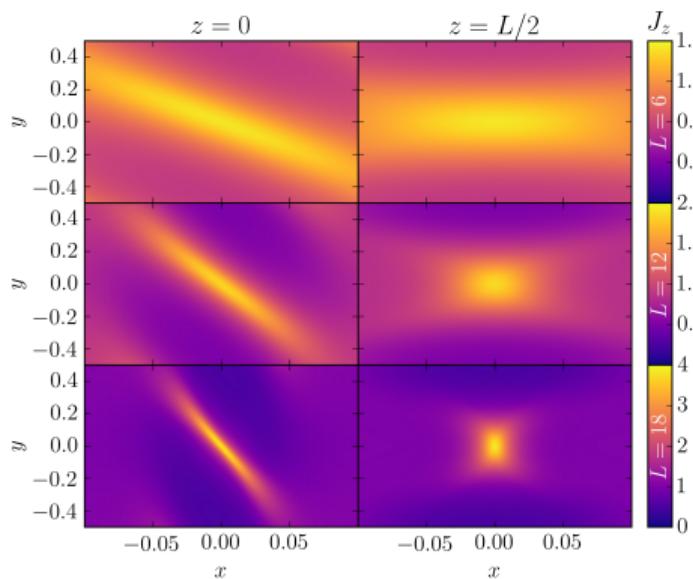


<sup>19</sup>Y. Zhou et al., *Astrophys. J.* 852, 3 (2018).

<sup>20</sup>D. W. Longcope and H. R. Strauss, *Astrophys. J.* 437, 851 (1994).

<sup>21</sup>C. S. Ng and A. Bhattacharjee, *Phys. Plasmas* 5, 4028 (1998).

# Longer systems: stronger shear tear up the mesh



Current density at footpoint and mid-plane

- Reduced MHD equilibrium equation,

$$\mathbf{B} \cdot \nabla j_z = 0. \quad (7)$$

- Singularity threaded through all  $z^{22}$ .
- In-plane field ( $z = z_0, B_{0z} = 1, J = 1$ ),

$$\mathbf{B}_\perp = \frac{\partial \mathbf{x}_\perp}{\partial \mathbf{x}_{0\perp}} \cdot \mathbf{B}_{0\perp} + \frac{\partial \mathbf{x}_\perp}{\partial z_0}. \quad (8)$$

- At the footpoints ( $\mathbf{x}_\perp = \mathbf{x}_{0\perp}$  at  $z = 0, L$ ),

$$j_z = j_{0z} + \hat{z} \cdot \nabla_\perp \times \frac{\partial \mathbf{x}_\perp}{\partial z_0}. \quad (9)$$

- Only the second term can be singular.
- Strong shear: an inherent feature.

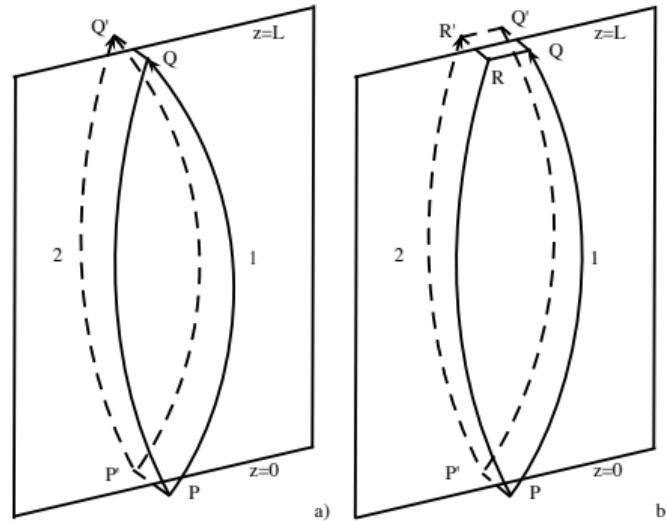
<sup>22</sup>A. A. van Ballegooijen, *Astrophys. J.* 298, 421 (1985).

# Summary and outlook

- Lagrangian labeling: the favorable description.
  - Built-in frozen-in equation.
  - Guaranteed invariance of magnetic topology.
- Numerical method: ideal MHD on a moving mesh.
  - No artificial reconnection.
  - Variational discretization; with discrete exterior calculus.
  - Re-meshing? Eulerian?
- Current singularity formation in 2D: conclusively confirmed.
  - Analytical and numerical solutions agree.
  - General mechanism in 2D.
  - Dynamics? Time scale?
- 3D line-tied geometry: inconclusive.
  - Smooth nonlinear solution for short systems.
  - Scaling suggests finite-length singularity.
  - Better discretization more robust against strong shear?
  - Generalize RDR's boundary-layer approach?

# On the impossibility of current singularities

- An existing proof<sup>23</sup> has an oversight.



- (a) Alleged contradiction:

$$\int_{1+2} B(l) [1 - \mathbf{b}_2(l) \cdot \mathbf{b}_1(l)] dl = 0. \quad (10)$$

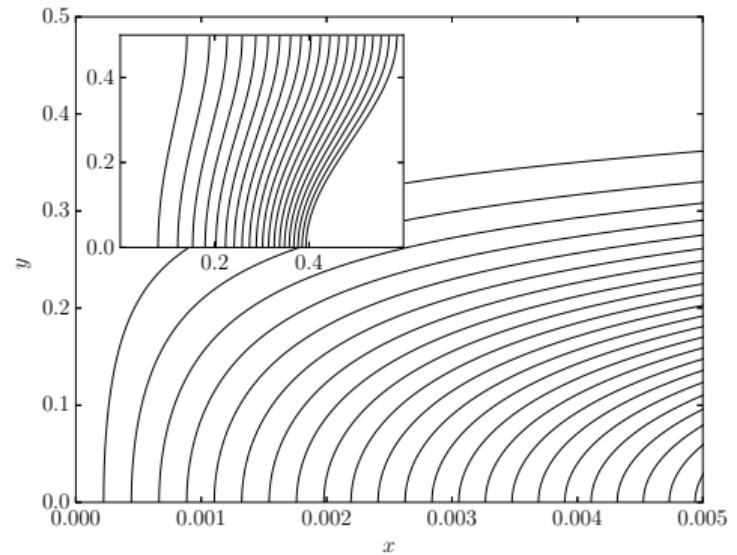
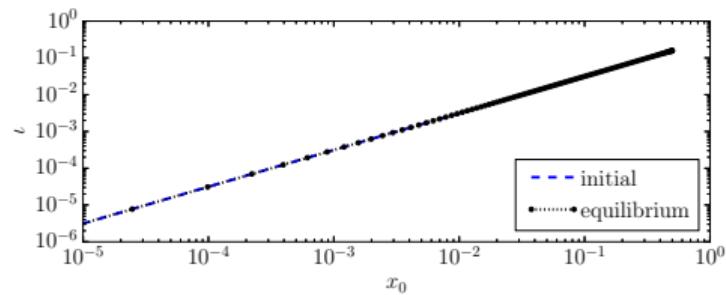
- (b) Accounting for the ‘hole’:

$$\begin{aligned} & \int_{1+2} B(l) [1 - \mathbf{b}_2(l) \cdot \mathbf{b}_1(l)] dl \\ &= \oint_{\partial\Omega} \mathbf{B} \cdot d\mathbf{l} = \int_{\Omega} \mathbf{j} \cdot d\mathbf{S}. \end{aligned} \quad (11)$$

- Magnetic shear keeps possibility alive.

<sup>23</sup>S. C. Cowley, D. W. Longcope, and R. N. Sudan, Phys. Rep. 283, 227 (1997).

# Discontinuous $\langle B_y \rangle$ but continuous rotational transform



Equilibrium solution: flux surfaces

- Rotational transform  $\iota \sim \langle B_y^{-1} \rangle^{-1}$ :
  - stays invariant and continuous;
  - contrary to a recent claim.

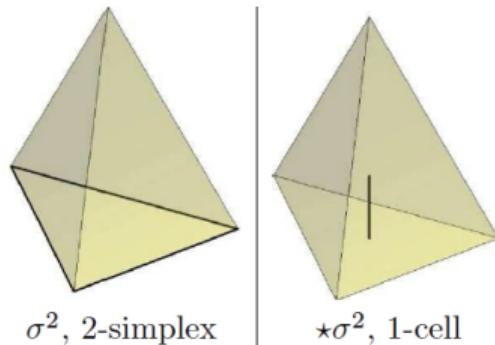
# Discrete Lagrangians and advection equations

- In Eulerian labeling  $(\sigma^k, t)$ : fixed mesh,

$$L(\mathbf{v}, \rho, p, \mathbf{B}) = \sum_{\sigma^3} \left[ \frac{\langle \rho, \sigma^3 \rangle}{8} \sum_{\sigma^0 \prec \sigma^3} \langle v^2, \sigma^0 \rangle - \frac{\langle p, \sigma^3 \rangle}{\gamma - 1} - \sum_{\sigma^2 \prec \sigma^3} \frac{|\star \sigma^2|}{2|\sigma^2|} \langle B, \sigma^2 \rangle^2 \right]. \quad (12)$$

- In Lagrangian labeling  $(\sigma_0^k, t)$ : moving mesh,

$$L(\mathbf{x}, \dot{\mathbf{x}}) = \sum_{\sigma_0^3} \left[ \frac{\langle \rho_0, \sigma_0^3 \rangle}{8} \sum_{\sigma_0^0 \prec \sigma_0^3} \dot{x}^2 - \frac{\langle p_0, \sigma_0^3 \rangle}{(\gamma - 1) J^{\gamma-1}} - \sum_{\sigma_0^2 \prec \sigma_0^3} \frac{|\star \sigma^2|}{2|\sigma^2|} \langle B_0, \sigma_0^2 \rangle^2 \right]. \quad (13)$$



- Discrete advection equations:

$$\langle \rho, \sigma^3 \rangle = \langle \rho_0, \sigma_0^3 \rangle, \quad (14a)$$

$$\frac{\langle p, \sigma^3 \rangle |\sigma^3|^{\gamma-1}}{\langle \rho, \sigma^3 \rangle^\gamma} = \frac{\langle p_0, \sigma_0^3 \rangle |\sigma_0^3|^{\gamma-1}}{\langle \rho_0, \sigma_0^3 \rangle^\gamma}, \quad (14b)$$

$$\langle B, \sigma^2 \rangle = \langle B_0, \sigma_0^2 \rangle. \quad (14c)$$